

## ON THE NUMERICAL SOLUTION OF INTEGRO-DIFFERENTIAL EQUATION

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Considering wide application of integro-differential equation, last time scientists from different countries have actively engaged in research of approximate solutions of integro-differential equations. Many of these scientists mainly are engaged in numerical solution of Volterra integro-differential equations. For this purpose, quadratic method, modification of the quadratic method, collocation method, etc. were investigated. Here we consider the use of implicit multistep methods with constant coefficients for solving Volterra integro-differential equations, and find sufficient conditions for its convergence.

**Introduction.** Consider the following initial-value problem for the integro-differential equations of Volterra type:

$$y'(x) = f(x, y) + \int_{x_0}^x K(x, s, y(s))ds, \quad y(x_0) = y_0. \quad (1)$$

Let's suppose continuous functions  $f(x, y)$  and  $K(x, s, y)$  are defined on some closed domain  $G$  and the problem (1) has the unique solution defined on the segment  $[x_0, X]$ . It is known that the problem (1) can be replaced by the next problem:

$$y'(x) = f(x, y) + v(x), \quad y(x_0) = y_0, \quad (2)$$

$$v(x) = \int_{x_0}^x K(x, s, y(s))ds. \quad (3)$$

For solving the system which consists of the relation (2) and (3), here we suggested following method:

$$\sum_{i=0}^k \alpha_i y_{n+i} = h \sum_{i=0}^k \beta_i f_{n+i} + h \sum_{i=0}^k \beta_i v_{n+i}, \quad (4)$$

$$\sum_{i=0}^k \alpha'_i v_{n+i} = h \sum_{j=0}^k \sum_{i=0}^k \gamma_{i,j} K(x_{n+j}, x_{n+i}, y_{n+i}), \quad (5)$$

where the coefficients  $\alpha_i, \alpha'_i, \beta_i, \gamma_{i,j}$  ( $i, j = 0, 1, \dots, k$ ) are some real numbers, and  $\alpha_k \neq 0, \alpha'_k \neq 0$ , a constant  $0 < h$  is a step of partitioning of the segment  $[x_0, X]$  into  $N$  equal parts, and the mesh points are defined in the form  $x_i = x_0 + ih$  ( $i = 0, 1, \dots, N$ ).

Here, at the mesh points  $x_m$  ( $m = 0, 1, 2, \dots$ ), the approximate values of the functions  $y(x)$  and  $v(x)$  are denoted by  $y_m$  and  $v_m$  ( $m = 0, 1, 2, \dots$ ), but exact values by  $y(x_m)$  and  $v(x_m)$  ( $m = 0, 1, 2, \dots$ ), respectively.

One of the important questions at researching method (4)-(5) is how much are closer the found values of the solution of a problem (1) by scheme (4) - (5) to exact values of the solution. Therefore consider convergence of the method (4) — (5) to the solution of the problem (1).

### §1. Convergence of $k$ -step method with the constant coefficients.

As is known, at real use of  $k$ -step method defined by scheme (4) and (5) there arises some round-off errors. Hence, the  $k$ -step method at real use will have the following form (see, f.e. [1]-[3]):

$$\sum_{i=0}^k \alpha_i y_{n+i} = h \sum_{i=0}^k \beta_i f_{n+i} + h \sum_{i=0}^k \beta_i v_{n+i} + \delta_n, \quad (1.1)$$

$$\sum_{i=0}^k \alpha'_i v_{n+i} = h \sum_{j=0}^k \sum_{i=0}^k \gamma_{i,j} K(x_{n+j}, x_{n+i}, y_{n+i}) + \delta'_n. \quad (1.2)$$

Here the round-off errors for the corresponding method are designated by  $\delta_n$  and  $\delta'_n$ .

As the sizes  $y_m$  and  $v_m$  ( $m=0,1,2,\dots$ ) are the approximate values of the solution of problem (2) and equation (3), it is natural that at replacement by their exact values in (4) and (5), we will receive some error which usually is called an error of methods. We have:

$$\sum_{i=0}^k \alpha_i y(x_{n+i}) = h \sum_{i=0}^k \beta_i f(x_{n+i}, y(x_{n+i})) + h \sum_{i=0}^k \beta_i v(x_{n+i}) + R_n, \quad (1.3)$$

$$\sum_{i=0}^k \alpha'_i v(x_{n+i}) = h \sum_{j=0}^k \sum_{i=0}^k \gamma_{i,j} K(x_{n+j}, x_{n+i}, y(x_{n+i})) + R'_n. \quad (1.4)$$

$R_n$  and  $R'_n$  are the errors of corresponding methods. Somebody can find the coefficients of method (5) by the way from [4].

The convergence of method (4)-(5) can be defined by means of the following theorem.

**Theorem 1.** Let the following conditions be satisfied:

1. Methods (4) and (5) are stable, and  $\alpha_k \neq 0$ ,  $\alpha'_k \neq 0$ .
2. Methods (4) and (5) have degree p.
3. Continuity on totality of variables of the functions  $f(x, y)$  and  $K(x, s, y)$  are defined in some closed domain they have partial derivatives to some p, inclusively.
4. The smallness order for the initial data  $y_m$  ( $m=0,1,\dots,k-1$ ) has the following form

$$y_m - y(x_m) = O(h^p), \quad v_m - v(x_m) = O(h^p).$$

5. Round-off errors have higher order smallness, than the initial data, namely:

$$\delta_n = O(h^{p+1}), \quad \delta'_n = O(h^{p+1}), \quad h \rightarrow 0.$$

Then it holds

$$\max_v((y(x_v) - y_v), (v(x_v) - v_v)) = O(h^p), \quad h \rightarrow 0. \quad (1.5)$$

Here the concept of stability and degree of a multistep method are defined just as in [5].

**Proof.** Subtracting (1.1) and (1.2) from (1.3) and (1.4), we have:

$$\varepsilon_{n+k} = \sum_{i=0}^{k-1} \frac{-\alpha_i + a_i h + b_i h^2}{\alpha_k - a_k h - b_k h^2} \varepsilon_{n+i} + h \sum_{i=0}^{k-1} \bar{\beta}_i \bar{\varepsilon}_{n+i} + \hat{R}_n, \quad (1.6)$$

$$\bar{\varepsilon}_{n+k} = -\sum_{i=0}^{k-1} \frac{\alpha'_i}{\alpha'_k} \bar{\varepsilon}_{n+i} + \frac{h}{\alpha'_k} \sum_{i=0}^k b_i \varepsilon_{n+i} + \hat{R}'_n, \quad (1.7)$$

where

$$a_i = \beta_i f'_y(x_{n+i}, \xi_{n+i}), \quad b_i = (\beta_k / \alpha'_k) \sum_{j=0}^k \gamma_{i,j} K'_y(x_{n+j}, x_{n+i}, \eta_{n+i}),$$

$$\hat{R}'_n = R'_n - \delta'_n;$$

$$\hat{R}_n = h \beta_k \hat{R}'_n / \alpha'_k + R_n - \delta_n / (\alpha_k - a_k h - b_k h^2),$$

$$\varepsilon_m = y(x_m) - y_m, \quad \bar{\varepsilon}_m = v(x_m) - v_m, \quad \bar{\beta}_i = \frac{\beta_i - \beta_k \alpha'_i / \alpha'_k}{\alpha_k - a_k h - b_k h^2},$$

$\xi_{n+i}$  and  $\eta_{n+i}$  are between  $y_{n+i}$  and  $y(x_{n+i})$ .

After some transformations, we can write relation (1.6) and (1.7) in the following form:

$$\varepsilon_{n+k} = -\sum_{i=0}^{k-1} \frac{\alpha_i}{\alpha_k} \varepsilon_{n+i} + h \sum_{i=0}^{k-1} \bar{\beta}_i \bar{\varepsilon}_{n+i} + h \sum_{i=0}^{k-1} e_i \varepsilon_{n+i} + h^2 \sum_{i=0}^{k-1} l_i \varepsilon_{n+i} + \hat{R}_n, \quad (1.8)$$

$$\bar{\varepsilon}_{n+k} = -\sum_{i=0}^{k-1} \frac{\alpha'_i}{\alpha'_k} \bar{\varepsilon}_{n+i} + h \sum_{i=0}^{k-1} (b_i + b_k d_i) \varepsilon_{n+i} + h^2 b_k \sum_{i=0}^{k-1} \bar{\beta}_i \bar{\varepsilon}_{n+i} + \hat{R}'_n + \frac{hb_k}{\alpha'_k} \hat{R}_n, \quad (1.9)$$

where

$$e_i = \frac{-\alpha_i a_k + a_i \alpha_k}{\alpha_k (\alpha_k - a_k h - b_k h^2)}, \quad l_i = \frac{-\alpha_i b_k + b_i \alpha_k}{\alpha_k (\alpha_k - a_k h - b_k h^2)}, \quad d_i = -\frac{\alpha_i}{\alpha_k} + h(e_i + hl_i).$$

After addition of the next identities:

$$\varepsilon_{n+i} = \varepsilon_{n+i}, \quad \bar{\varepsilon}_{n+i} = \bar{\varepsilon}_{n+i} \quad (i = 0, 1, 2, \dots, k-1)$$

rewrite the received system of the equations by means of the following vectors

$$Y_{n+k} = (\varepsilon_{n+k}, \varepsilon_{n+k-1}, \dots, \varepsilon_{n+1}), \quad \bar{Y}_{n+k} = (\bar{\varepsilon}_{n+k}, \bar{\varepsilon}_{n+k-1}, \dots, \bar{\varepsilon}_{n+1})$$

in the form:

$$Y_{n+k} = AY_{n+k-1} + hB\bar{Y}_{n+k-1} + hB_1 Y_{n+k-1} + h^2 B_2 Y_{n+k-1} + W_n, \quad (1.10)$$

$$\bar{Y}_{n+k} = A'\bar{Y}_{n+k-1} + hVY_{n+k-1} + h^2 V_1 \bar{Y}_{n+k-1} + \bar{W}_n, \quad (1.11)$$

where

$$A = \begin{pmatrix} -\frac{\alpha_{k-1}}{\alpha_k} & -\frac{\alpha_{k-1}}{\alpha_k} & \dots & -\frac{\alpha_1}{\alpha_k} & -\frac{\alpha_0}{\alpha_k} \\ \frac{\alpha_k}{\alpha_k} & \frac{\alpha_k}{\alpha_k} & \dots & \frac{\alpha_k}{\alpha_k} & \frac{\alpha_k}{\alpha_k} \\ 1 & 0 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}, \quad A' = \begin{pmatrix} -\frac{\alpha'_{k-1}}{\alpha'_k} & -\frac{\alpha'_{k-1}}{\alpha'_k} & \dots & -\frac{\alpha'_1}{\alpha'_k} & -\frac{\alpha'_0}{\alpha'_k} \\ \frac{\alpha'_k}{\alpha'_k} & \frac{\alpha'_k}{\alpha'_k} & \dots & \frac{\alpha'_k}{\alpha'_k} & \frac{\alpha'_k}{\alpha'_k} \\ 1 & 0 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix},$$

$$B = \begin{pmatrix} \bar{\beta}_{k-1} & \bar{\beta}_{k-1} & \dots & \bar{\beta}_0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix}, \quad B_1 = \begin{pmatrix} e_{k-1} & e_{k-2} & \dots & e_0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix}, \quad B_2 = \begin{pmatrix} l_{k-1} & l_{k-2} & \dots & l_0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix},$$

$$V = \begin{pmatrix} v_{k-1} & v_{k-2} & \dots & v_0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix}, \quad V_1 = \begin{pmatrix} \bar{\beta}_{k-1} & \bar{\beta}_{k-2} & \dots & \bar{\beta}_0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix}, \quad \bar{W}_{n,k} = \begin{pmatrix} \bar{R}_n \\ 0 \\ \vdots \\ 0 \end{pmatrix}; \quad W_{n,k} = \begin{pmatrix} \bar{R}_n \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$v_i = (b_i + b_k \bar{d}_i) / \alpha_k, \quad \bar{d}_i = (-\alpha_i + a_i h + b_i h^2) / (\alpha_k - a_k h - b_k h^2).$$

By the vector  $Z_{n+k} = (Y_{n+k}, \bar{Y}_{n+k})$  we will write the equations (1.10) and (1.11) in the following form:

$$Z_{n+k} = \bar{A}Z_{n+k-1} + h\bar{B}Z_{n+k-1} + h^2 \bar{B}Z_{n+k-1} + \bar{W}_n, \quad (1.12)$$

where

$$\bar{A} = \begin{pmatrix} A & 0 \\ 0 & A' \end{pmatrix}, \quad \bar{B} = \begin{pmatrix} B_1 & B \\ V & 0 \end{pmatrix}, \quad \bar{B} = \begin{pmatrix} B_2 & 0 \\ 0 & V_1 \end{pmatrix}, \quad \bar{W}_n = \begin{pmatrix} W_n \\ \bar{W}_n \end{pmatrix}.$$

On theorem conditions, characteristic numbers of a matrix  $A$  and  $A'$  are in a unit circle on whose border there are no multiple roots. Then there is a block matrix  $C$  such that  $\|D\| = \|C^{-1} \bar{A} C\| \leq 1$  [6].

In the equation (1.12) we use replacement  $Z_m = CT_m$ . Then, multiplying the received equation at the left by  $C^{-1}$ , we have:

$$T_m = DT_{m-1} + hS_1T_{m-1} + h^2S_2T_{m-1} + w_m. \quad (1.13)$$

Here,

$$D = C^{-1}AC, S_1 = C^{-1}BC, S_2 = C^{-1}\check{B}C, w_m = C^{-1}\check{W}_m.$$

It is easy to show that the norm of matrices  $S_1, S_2$  and a vector  $w_m$  are limited i.e.

$$\|S_1\| \leq M_1, \|S_2\| \leq M_2, \|w_m\| \leq M_3 \max(R_m, R'_m).$$

Passing in norm in the equation (1.13), we have

$$\|T_m\| \leq M_3 |\bar{R}_j| + (1 + h\gamma) \|T_{m-1}\|, \quad (1.14)$$

where  $\bar{R}_m = \max(R_m, R'_m)$ ,  $\gamma = M_1 + hM_2$ .

By means of mathematical induction, from (1.14) we will receive

$$\|T_m\| \leq M_3 \sum_{j=k}^m (1 + h\gamma)^{m-j} |\bar{R}_j| + (1 + h\gamma)^{m-k+1} \|T_{k-1}\|. \quad (1.15)$$

Simplifying this estimation and using the following inequality

$$(1 + h\gamma)^{m-j} \leq \exp(h\gamma(m-j)) \leq \exp(h\gamma m)$$

from (1.15) we have:

$$\|T_m\| \leq \exp(h\gamma m) (M_3 \sum_{j=k}^m |\bar{R}_j| + \|T_{k-1}\|).$$

It is clear that the next inequality is valid:

$$\max(\varepsilon_m, \bar{\varepsilon}_m) \leq \|Z_m\| \leq \|C\| \|T_m\|.$$

Hence

$$\max(\varepsilon_m, \bar{\varepsilon}_m) \leq \exp(h\gamma m) (M_3 \|C\| \sum_{j=k}^m |\bar{R}_j| + \|C\| \|T_{k-1}\|).$$

From here

$$\max(\varepsilon_m, \bar{\varepsilon}_m) \leq \exp(\gamma X m) (\bar{M}_3 \sum_{j=k}^m |\bar{R}_j| + \|C\| \|C^{-1}\| \max_{0 \leq i \leq k-1} (\varepsilon_i, \bar{\varepsilon}_i)). \quad (1.16)$$

Considering in (1.16) theorem conditions, we will receive

$$\max(\varepsilon_m, \bar{\varepsilon}_m) = O(h^p), \quad h \rightarrow 0.$$

The theorem is proved.

## References

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